

## Thermoelastic properties of $\alpha$ -iron from first-principles

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We calculate the thermomechanical properties of  $\alpha$ -iron, and in particular its isothermal and adiabatic elastic constants, using first-principles total-energy and lattice-dynamics calculations, minimizing the quasiharmonic vibrational free energy under finite strain deformations. Particular care is made in the fitting procedure for the static and temperature-dependent contributions to the free energy, in discussing error propagation for the two contributions separately, and in the verification and validation of pseudopotential and all-electron calculations. We find that the zero-temperature mechanical properties are sensitive to the details of the calculation strategy employed, and common semilocal exchange-correlation functionals provide only fair to good agreement with experimental elastic constants, while their temperature dependence is in excellent agreement with experiments in a wide range of temperature almost up to the Curie transition.

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### I. INTRODUCTION

Elemental iron is a material of great scientific and economic interest: it is the major constituent of steels, it determines the properties of the earth core, and its complex phase diagram is driven by the subtle interplay between vibrational and magnetic contributions, making it particularly challenging to describe accurately from first-principles. This is especially relevant as temperature increases, since magnetic excitations become important and a dramatic change in the magnetic nature of the system takes place. At ordinary pressures, iron turns from a bcc ferromagnet to a bcc paramagnet with a second-order transition ( $\alpha \rightarrow \beta$ ) at a Curie temperature of  $\sim 1043$  K. This transition is then followed by two structural transitions, a bcc  $\rightarrow$  fcc ( $\beta \rightarrow \gamma$ ) transition at 1185 K and a fcc  $\rightarrow$  bcc ( $\gamma \rightarrow \delta$ ) transition at 1670 K, before finally melting at  $\sim 1814$  K.

First-principles simulations can be a key technique and a valid alternative to experiments in order to get accurate predictions of phase diagrams without the need of phenomenological parameters, and they become essential at conditions that are challenging to reproduce in real life, such as those inside the earth's core [1]. For the case of pressure-temperature phase diagrams, zero-temperature first-principles equations of state can be supplemented with finite-temperature vibrational entropies, which can be derived directly from the knowledge of the phonon dispersions. These latter can be calculated from finite differences, or more elegantly and less expensively with density-functional perturbation theory (DFPT) [2,3]. When coupled to the quasiharmonic approximation [4] (QHA), these techniques allow us to calculate thermal expansion and vibrational properties at finite temperatures, often well above the Debye temperature [5–11]. While there have been numerous first-principles calculations of elastic properties of solids by either total energy, stress-strain [12,13], or density-functional perturbation theory approaches [14–16], a relatively limited number of them have been focused on the thermomechanical properties of metals or minerals [17–20].

In this paper, we calculate the adiabatic and isothermal finite-temperature elastic properties of ferromagnetic  $\alpha$ -iron

in its temperature range of stability and at ambient pressure using the QHA and DFPT. We also carefully explore multi-dimensional fitting procedures for the static and vibrational contributions to the free energy, and we analyze the quality of the fit and the source of errors of both contributions, providing a confidence interval of each elastic constant as a function of temperature.

The paper is organized as follows: In Sec. II we introduce the finite strain framework used to calculate the elastic constants, and in Sec. III we give the computational details of our first-principles density-functional theory (DFT) and DFPT calculations. We present our results and their comparison to experiments in Sec. IV. Finally, Sec. V is devoted to summary and conclusions.

### II. FINITE-STRAIN METHOD

In the limit of small deformations, the energy of a crystal at an arbitrary configuration can be Taylor-expanded in terms of a symmetric matrix  $\boldsymbol{\epsilon}$  describing a uniform linear deformation  $\mathbf{A}$  such that

$$\mathbf{A} = \mathbf{1} + \boldsymbol{\epsilon}, \quad (1)$$

and any position vector  $\bar{r}$  in the reference configuration is transformed into  $(\mathbf{1} + \boldsymbol{\epsilon}) \cdot \bar{r}$ . The isothermal elastic constants at zero pressure are then defined as the second-order coefficients of this expansion according to [21]

$$C_{ij}^T = \left. \frac{1}{V_0} \frac{\partial^2 F}{\partial \epsilon_i \partial \epsilon_j} \right|_{V_0, T}, \quad (2)$$

where  $F$  is the Helmholtz free-energy, and  $\epsilon_i, \epsilon_j$ ,  $i, j = 1, \dots, 6$ , are the components of the strain tensor  $\boldsymbol{\epsilon}$  (we adopt here the Voigt notation). Also, note that the second derivatives are evaluated at the thermodynamic equilibrium configuration with volume  $V_0$  and at constant temperature  $T$ .

For cubic crystals, such as  $\alpha$ -iron, only three elastic constants are needed to completely determine the stiffness tensor and, therefore, fully characterize the mechanical response of the system in the linear elastic regime. As a consequence, only

TABLE I. Deformations and corresponding strain vectors in the Voigt notation: <sup>(1)</sup>hydrostatic, <sup>(2)</sup>tetragonal, and <sup>(3)</sup>trigonal deformations are governed by a single parameter. Note that the trigonal deformation reported here is the first-order expansion of the full strain tensor  $\boldsymbol{\epsilon}^{(3)}$  with nonzero off-diagonal terms (denoted by an asterisk).

$\boldsymbol{\epsilon}^{(i)}$	$\epsilon_1$	$\epsilon_2$	$\epsilon_3$	$\epsilon_4$	$\epsilon_5$	$\epsilon_6$
$\boldsymbol{\epsilon}^{(1)}$	$\epsilon_a$	$\epsilon_a$	$\epsilon_a$	0	0	0
$\boldsymbol{\epsilon}^{(2)}$	0	0	$\epsilon_c$	0	0	0
$\boldsymbol{\epsilon}^{(3)*}$	0	0	0	$\epsilon_d/2$	$\epsilon_d/2$	$\epsilon_d/2$

three independent deformations are sufficient, and we choose here the hydrostatic, tetragonal, and trigonal deformations, shown in Table I. Each deformation fully determines one of the cubic elastic constants (or elastic moduli).

To compute finite-temperature properties and, therefore, to calculate the Helmholtz free energy  $F$ , the vibrational contribution must be added to the static energy term. The QHA [4] provides an analytical expression for the vibrational contribution to the free energy:

$$F(\{a_i\}, T) = \underbrace{E_{\text{stat}}(\{a_i\})}_{\text{static}} + \underbrace{\frac{1}{2} \sum_{\mathbf{q}, \lambda} \hbar \omega_{\mathbf{q}, \lambda}(\{a_i\})}_{\text{ZPE}} + \underbrace{k_B T \sum_{\mathbf{q}, \lambda} \ln \left( 1 - e^{-\frac{\hbar \omega_{\mathbf{q}, \lambda}(\{a_i\})}{k_B T}} \right)}_{\text{thermal}}, \quad (3)$$

where the sum is performed over all the phonon modes  $\lambda$  and all the phonon wave vectors  $\mathbf{q}$  spanning the Brillouin zone (BZ). Here,  $k_B$  is the Boltzmann constant and  $\omega_{\mathbf{q}, \lambda}$  are the vibrational frequencies of the different phonon modes, where in the QHA their explicit dependence on the geometry of the system via the primitive lattice vectors  $\{a_i\}$  is accounted for. The vibrational part, coming directly from the analytic partition function of a Bose-Einstein gas of harmonic oscillators, can be split into a zero-point energy term plus a contribution that depends explicitly on the temperature  $T$ . We neglect here the thermal electronic effects, because they are believed to be relatively small compared to the quasiharmonic vibrational contribution [11,22] in the range of stability of the  $\alpha$  phase. Magnetic effects are also not considered, except for the longitudinal relaxation of the total magnetic moment as a function of strain, but they are known to be important approaching the Curie point [23–25], and their influence on the elastic properties is briefly discussed in Sec. IV C in the light of previous studies.

Equation (2) is used to calculate the isothermal elastic constants at finite temperature; however, in order to compare results with experimental data obtained from ultrasonic measurements [26], we also calculate the adiabatic elastic constants, using the following relations [21]:

$$\begin{aligned} C_{11}^{(S)} - C_{11}^{(T)} &= C_{12}^{(S)} - C_{12}^{(T)} \\ &= B^{(S)} - B^{(T)} = \frac{TV\alpha^2 B^{(T)2}}{C_V}, \\ C_{44}^{(S)} - C_{44}^{(T)} &= 0, \end{aligned} \quad (4)$$

where the heat capacity at constant volume  $C_V$  and the volumetric thermal expansion coefficient  $\alpha$  are both calculated from the QHA. The superscripts  $(S)$  and  $(T)$  define the adiabatic and isothermal elastic constants  $C_{ij}$  and bulk modulus  $B$ , respectively.

### III. COMPUTATIONAL DETAILS AND PSEUDOPOTENTIAL SELECTION

We calculate the first-principles elastic constants using DFT, as implemented in the PWSCF and PHONON packages of the QUANTUM-ESPRESSO distribution [27] for the static and lattice dynamical calculations, respectively. The calculations are spin-polarized and the magnetic moment is free to vary collinearly in order to minimize the total energy. In all calculations, the exchange-correlation effects have been treated within the generalized-gradient approximation (GGA) with the PBE functional [28]. We use an ultrasoft pseudopotential [29] (USPP) from *pslibrary.0.3.0* [30], which includes also 3s and 3p semicore states [31] (i.e., 16 valence electrons) along with a plane-wave basis with a wave-function kinetic-energy cutoff of 90 Ry and a cutoff of 1080 Ry for the charge density. We sampled the BZ with an offset  $24 \times 24 \times 24$  Monkhorst-Pack  $k$ -mesh, with a Marzari-Vanderbilt smearing [32] of 0.005 Ry.

Phonon calculations were carried out for each deformation within DFPT [3]: the dynamical matrix and its eigenvalues are calculated on a  $4 \times 4 \times 4$  mesh of special points in the BZ and Fourier-interpolated on an extended  $21 \times 21 \times 21$  grid for the integration of thermodynamic quantities. We arrived at this computational setup (cutoff, smearing, and BZ sampling) after a careful investigation of the convergence of total energy

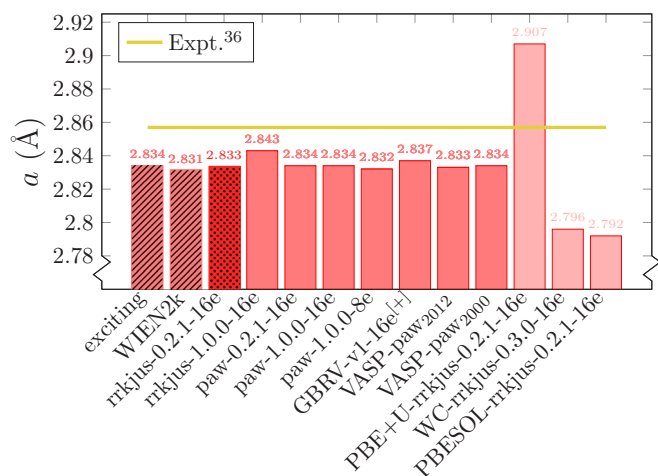


FIG. 1. (Color online) Equilibrium lattice parameter at 0 K for the different iron pseudopotentials tested in this work. All the data shown here are obtained with the PBE XC functional except for the last three columns on the right, where we have used PBE+U [37–40], WC [41], and a PBEsol [42], respectively (here we use a Hubbard  $U$  correction, with  $U = 3$  eV). The data come from a Birch-Murnaghan fit, do not include zero-point energy, and are compared to all-electron WIEN2K [43], exciting [44], and VASP [35] calculations from Refs. [45–47], respectively, and experiments [36,48,49] (horizontal yellow line). The crosshatch dotted column corresponds to the pseudopotential chosen for the production runs.

and individual phonon frequencies for different deformations. Also, we verified that individual total energies and phonon frequencies do change smoothly as a function of strain.

Since the choice of the pseudopotential is of primary importance for a clear comparison with computational and experimental data in the literature, it is worth stressing that the one used here has been chosen among different candidates from the *pslibrary* [33] and *GBRV* library [34] to reproduce, as closely as possible, the all-electron FLAPW equilibrium lattice parameter, bulk modulus at 0 K, and local magnetization obtained from independent groups. Also, for the sake of completeness, we compare against results obtained using the VASP code and associated pseudopotentials [35].

The results for the lattice parameter and bulk modulus of the different pseudopotentials herein considered are reported in Figs. 1 and 2, and are obtained from a Birch-Murnaghan fit of calculated  $E(V)$  data points. Interestingly, we have found that the volume range of validity for fitting a Birch-Murnaghan curve is limited on the expansion side due to anomalies in the  $E(V)$  curve and its derivatives. These anomalies, also reported for all-electron and other calculation methods in Ref. [52], are more clearly visible as “shoulders” in the  $M(V)$  behavior (see Fig. 3) and, as visible from Fig. 4, can be associated with a smooth magnetic transition from a low to high spin state due to the splitting of the majority and minority spin  $t_{2g}$  electrons upon increasing the volume. However, for the pseudopotential chosen here, the expanded volumes at which this anomaly is observed (above 9% [53]) are far beyond the theoretical thermal expansion of the system in the thermodynamic region considered in this work, thus enabling us to fit the energy

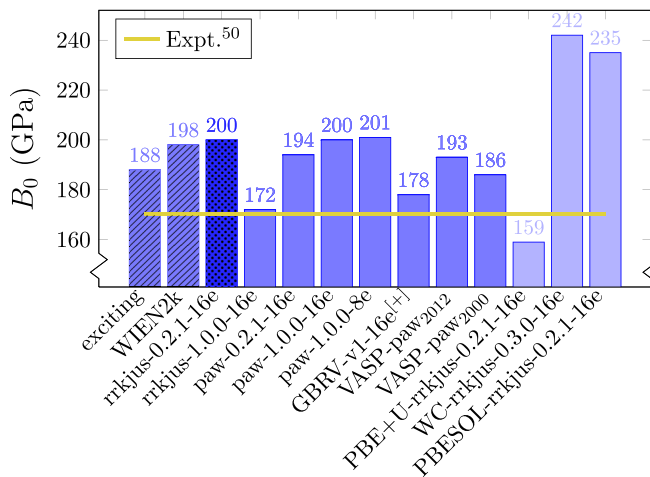


FIG. 2. (Color online) Equilibrium bulk moduli at 0 K for the different iron pseudopotentials tested in this work. All the data shown here are obtained with the PBE XC functional except for the last three columns on the right, where we have used PBE+U [37–40], WC [41], and a PBEsol [42], respectively (here we use a Hubbard  $U$  correction with  $U = 3$  eV). The data come from a Birch-Murnaghan fit, do not include zero-point energy, and are compared to all-electron WIEN2K [43], exciting [44], and VASP [35] calculations from Refs. [45–47], respectively, and experiments [50] (horizontal yellow line). The crosshatch dotted column corresponds to the pseudopotential chosen for the production runs.

surface with volume expansions up to  $\sim 9\%$  still using a standard Birch-Murnaghan equation.

## IV. RESULTS

In this section we present results for selected thermodynamic quantities and for the three strain deformations (hydrostatic or volumetric, tetragonal, and trigonal). Each deformation determines uniquely one of the three elastic constants:  $B$  (bulk modulus),  $C_{11}$ , and  $C_{44}$ , respectively.

### A. $B$ —Volumetric strain

The volumetric deformation  $\epsilon^{(1)}$  can be described by a single parameter  $\epsilon_a$ , namely, the strain of the cubic lattice parameter (see Table I). Thus, the lattice spacing is defined as

$$a = a_0(1 + \epsilon_a), \quad (5)$$

where  $a_0$  is the theoretical equilibrium lattice parameter without zero-point contribution (see Table III). The static part of the Helmholtz free energy of Sec. II is obtained by fitting a Birch-Murnaghan equation of state [54] to a

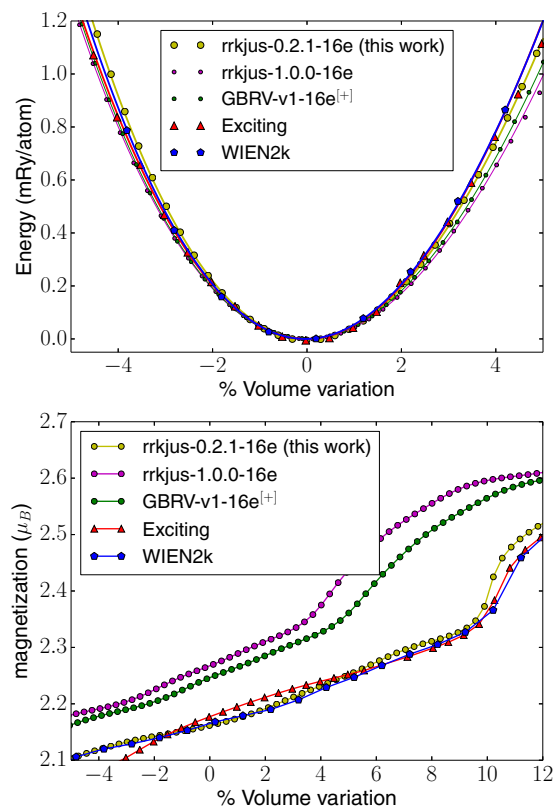


FIG. 3. (Color online) (Top panel) Equation of state as a function of percent volume change with respect to the theoretical equilibrium configurations for three of the selected PBE pseudopotentials considered in this work (circles). The yellow circles best match the all-electron WIEN2K [43] (pentagons) and exciting [44] (triangles) results from Refs. [46,51] and correspond to the rrkjus-0.2.1-16e pseudopotential used in this work. Continuous lines are the best fit of the Birch-Murnaghan equation. (Bottom panel) Total magnetization as a function of percent volume change. The soft magnetic transition discussed in the text is visible as a clear change in the average slope of the different curves.

series of well-converged total energy values calculated on a one-dimensional regular grid with  $\varepsilon_a$  going from  $-0.02$  to  $+0.03$  in steps of  $0.001$ . The resulting static contribution to the bulk modulus is reported in Table III. The vibrational contribution, on the other hand, has been calculated on a coarser grid via integration of the phonon dispersions as from Eq. (3) (examples for the calculated phonon dispersion and resulting Grüneisen parameters can be found in Fig. 5), with  $\varepsilon_a$  ranging from  $-0.012$  to  $+0.020$  in increments of  $0.004$  and fitted with a second-order polynomial as a function of the strain parameter  $\varepsilon_a$ . The stability of the results has been checked against a fit with lower- and higher-order polynomials (see the Supplemental Material [55]).

The free energy is then obtained as an analytical function of  $\varepsilon_a$  and  $T$  and is shown in Fig. 6. We then determined the thermal expansion (Fig. 6), the thermal expansion coefficients (Fig. 7), the heat capacity (Fig. 7), and the isothermal bulk modulus  $B^{(T)}(T)$  from the analytic second derivative of the

free energy as in Eq. (1). The adiabatic correction of Eq. (4) is then used to compute the adiabatic bulk modulus  $B^{(S)}(T)$ . Results are reported in Fig. 8 and compared to experimental data from Refs. [26,50]. The agreement between experiments and calculations in the thermal behavior of the bulk modulus is remarkable, especially below the Debye temperature ( $\Theta_D \simeq 500$  K). Above  $\Theta_D$ , the small deviation from experiments can be ascribed to magnetic fluctuations [25,26,63,64] that become increasingly important approaching the Curie temperature (1043 K), plus minor contributions from anharmonic effects (beyond quasiharmonic) and from the electronic entropy. At 1000 K, the softening of the calculated  $B^{(S)}$  is nearly 15% with respect 0 K. The calculated magnetic moment increases from  $2.17\mu_B$  per atom ( $2.22\mu_B$  from experiments [65]) at the 0 K equilibrium volume to  $2.27\mu_B$  at the 1000 K equilibrium volume. Obviously, transverse magnetic fluctuations are neglected in these calculations, and we postpone to Sec. IV C the discussion on the mismatch between experiments and calculations in absolute values.

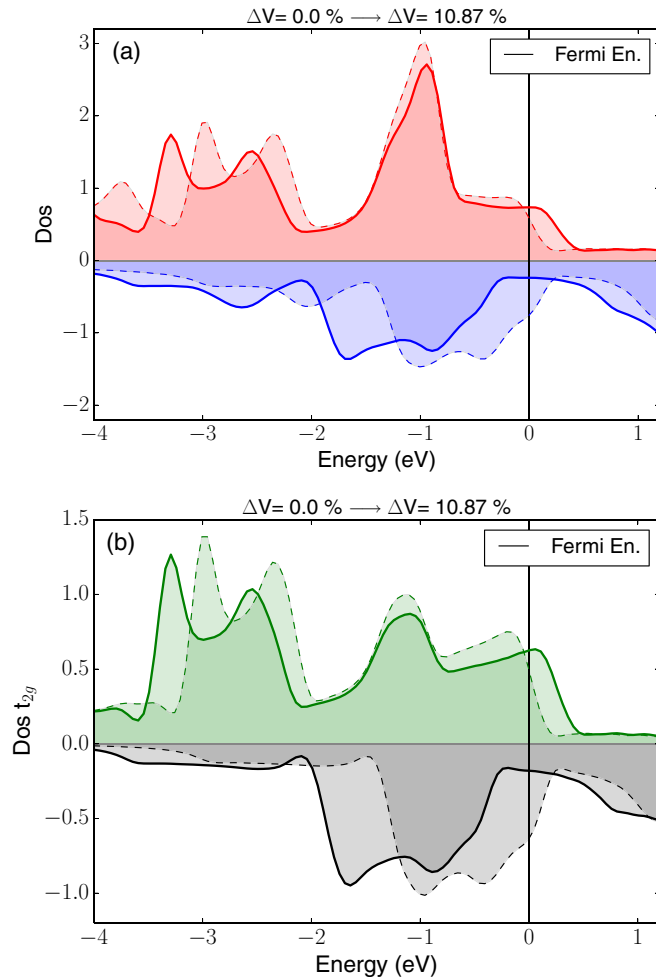


FIG. 4. (Color online) (a) DOS of majority (minority) [red (blue)] spin channels at the equilibrium (solid line) and  $\Delta V \approx 11\%$  (dashed line) where, for the pseudopotential used in the production run, the magnetic transition takes place. (b) The contribution of the  $t_{2g}$  electrons to the majority (minority) DOS [green (black)] is also reported. To obtain a smooth DOS, a non-self-consistent calculation with an offset  $60 \times 60 \times 60$  Monkhorst-Pack  $k$ -mesh is performed on top of a SCF loop.

### B. $C_{11}, C_{44}$ —Tetragonal and trigonal strains

The Helmholtz free energy  $F$  depends upon two strain parameters: the isotropic lattice strain  $\varepsilon_a$  and a second strain parameter  $\varepsilon_c$  or  $\varepsilon_d$  according to the deformation considered (see Table I).

The tensor  $\mathbf{e}^{(2)}$  is associated with a continuous tetragonal deformation that stretches the edge  $c$  of the cubic undistorted structure along the  $z$  axis while leaving unchanged the other edges. The relation between the strain  $\varepsilon_c$  and the distorted edge  $c$  is

$$c = a(1 + \varepsilon_c). \quad (6)$$

The tensor  $\mathbf{e}^{(3)}$  is associated with a continuous trigonal deformation that stretches the main diagonal  $d$  of the undistorted cubic structure along the (111) direction while tilting the undistorted edges and preserving their length. In this case, the relation between the strain  $\varepsilon_d$  and the distorted main diagonal is

$$d = \sqrt{3}a(1 + \varepsilon_d), \quad (7)$$

while the relation with the cosine of the angle between the distorted edges is

$$\cos(\alpha) = \frac{1 - \varepsilon_d(2 + \varepsilon_d)}{(\varepsilon_d - 1)(\varepsilon_d + 3)}. \quad (8)$$

Both deformations do not conserve the volume per atom. In particular, in the tetragonal one the volume increases as a function of  $\varepsilon_c$ , while in the trigonal case, the volume decreases as a function of  $\varepsilon_d$ . Alternatively, we could have chosen volume-conserving deformations as in Ref. [17], but the advantage of the present scheme is that each deformation determines uniquely one elastic constant at a time, and it enables us to determine easily the confidence interval of each elastic constant by error-propagation theory.

In the next subsections, we describe the calculation of the static and vibrational contributions separately. The reason is that we want to analyze their contributions to the global energy landscape separately. This also allows us to sample the two contribution landscapes with two different grids. Indeed, the

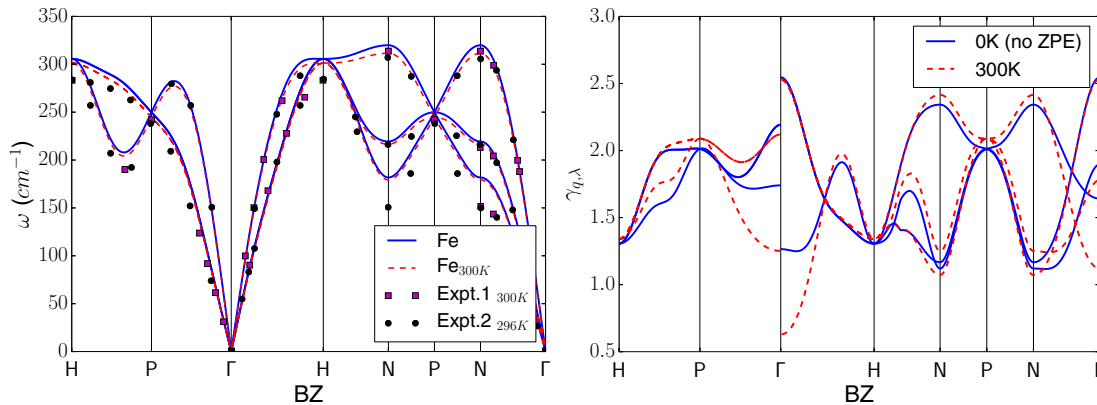


FIG. 5. (Color online) (Left panel) Phonon dispersions along high-symmetry directions in the BZ calculated at the theoretical electronic equilibrium volume (blue solid line) and at the quasiharmonic theoretical equilibrium volume at 300 K (red dashed line). The results (see also Fig. 1 in the Supplemental Material [55] and Ref. [8] or Ref. [56] for comparison with previous theoretical data) are compared to experimental data at room temperature from Ref. [57] (Expt. 1, squares) and Ref. [58] (Expt. 2, circles). (Right panel) Grüneisen parameters calculated along the same path in the BZ and the same equilibrium volumes used for the phonon dispersion (blue solid line for the 0 K case and red dashed line for the 300 K case). The Grüneisen parameters are obtained computing the first derivative with respect to the volume of a cubic fit of the phonon frequencies.

static term displays a minimum as a function of the strain parameters and has to be sampled with a dense grid, while, on the other hand, the vibrational term is flat, monotonic, and can be sampled with a coarse grid.

### 1. Static contribution

To evaluate the static contribution to the elastic constants, we performed a series of well-converged total energy calculations on a two-dimensional discrete grid  $[\varepsilon_a, \varepsilon_{c/d}]$  (see Fig. 9 for details on the grid). The  $\varepsilon_a$  grid is asymmetric with respect to zero and with more points in the positive range of the strain parameter, in order to sample accurately the values of the static contribution to the free energy also in the thermal expansion range. The resulting total energies are fitted with a two-dimensional bivariate polynomial up to fifth degree using a least-squares method [66].

The analysis of the quality of the fit of discrete data points to a two-dimensional energy surface is crucial to resolve the possible sources of error that could affect our elastic constants and, therefore, for a reliable comparison with experiments and the wide range of scattered data available in the literature. Therefore, in addition to the visual inspection of the fit along constant  $\varepsilon_{c/d}$  sections, we evaluated the adjusted coefficient of determination ( $R^2$ ) and the average absolute error (AAE), defined as

$$\text{AAE} \equiv \frac{1}{N} \sum_{i,j} |P_n(\varepsilon_a^{(i)}, \varepsilon_{c/d}^{(j)}) - E(\varepsilon_a^{(i)}, \varepsilon_{c/d}^{(j)})|, \quad (9)$$

where  $N$  is the total number of  $[\varepsilon_a, \varepsilon_{c/d}]$  discrete values and  $P_n$  is the bivariate polynomial of degree  $n$ . Thus,  $R^2$  is a measure of the quality of the fitting model, i.e., how well the analytic function approximates the calculated data points. The AAE is a quantitative measure of the distance of the fitted curve from the calculated points. We found that the AAE decreases by increasing the degree  $n$  of the polynomial and  $R^2$  approaches unity, as shown in Table II. According to these results, in both

cases we considered the fourth-degree polynomial to provide a sufficiently accurate fit (indeed the AAE is two orders of magnitude smaller than the difference between the highest and the lowest total-energy data points).

Figure 9 shows a plot of the static energy landscape for both the tetragonal and trigonal deformations, with the minimum elongated along the diagonal in the  $[\varepsilon_a, \varepsilon_c]$  space or along constant  $\varepsilon_d$  in the  $[\varepsilon_a, \varepsilon_d]$  space.

### 2. Vibrational contribution

To evaluate the vibrational contributions to the free energy, we performed a series of linear-response phonon calculations on a two-dimensional grid in the space of deformation scalars  $\varepsilon_a, \varepsilon_{c/d}$ . Since the lattice dynamics calculations are one order of magnitude more time-consuming than the total energy calculations, we used a coarser grid (see Fig. 10 for details on the grid).

The eigenvalues of each dynamical matrix are Fourier-interpolated in order to obtain smooth and continuous phonon dispersions. The zero-point energy and the thermal contributions are calculated by numerical integration over  $21 \times 21 \times 21$  points in reciprocal space. This is essential to obtain numerically accurate values of the vibrational contribution.

As for the case of the static contribution, we determined the best polynomial necessary to fit our data over the entire temperature range from 0 to 1000 K. Similarly, we used the adjusted  $R^2$  and the AAE as indicators of the quality of the fit. Our choice of polynomial is dictated by the need to minimize the AAE, maximize  $R^2$ , and minimize the confidence interval (see Sec. IV B 3 for details on its calculation) at each temperature. We also checked *a posteriori* the stability of the computed elastic constant curves against different polynomial degrees (see the Supplemental Material [55]). In the tetragonal case, a quadratic bivariate polynomial (i.e., six parameters) is sufficient to accurately reproduce

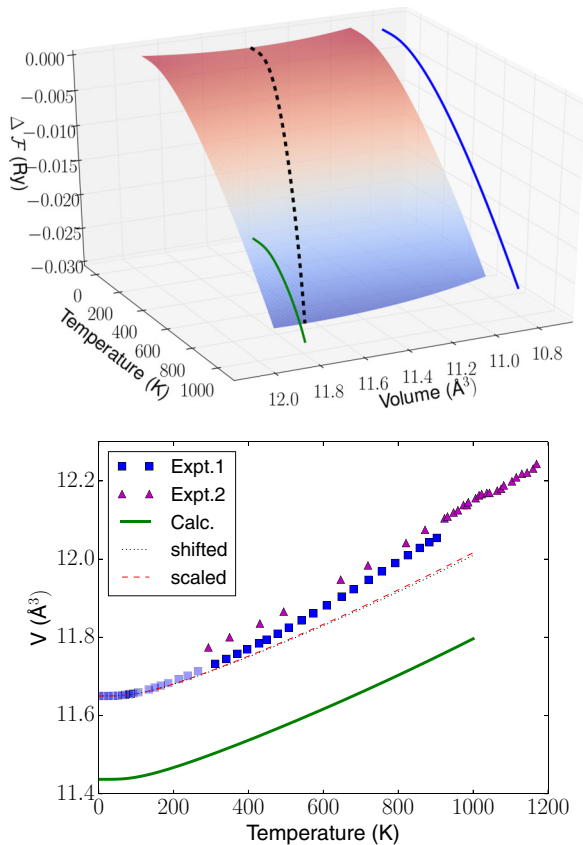


FIG. 6. (Color online) (Top panel) Free-energy landscape of cubic bcc iron as a function of volume  $V$  and temperature  $T$ . The dashed black line corresponds to the set of points that minimize the free-energy surface at each temperature. The continuous green and blue lines are the projections of the black dashed line in the  $T$ - $V$  and  $F$ - $T$  planes, thus describing the volumetric thermal expansion and the zero-pressure free energy as a function of  $T$ . (Bottom panel) Volumetric thermal expansion (green solid line) compared to experimental data from Ref. [36] (Expt. 1, blue squares; note that below room temperature, the data are extrapolated according to the thermal expansion coefficient of Ref. [49]) and Ref. [59] (Expt. 2, magenta triangles). As a guide to the eye, we also report in all plots shifted and scaled quantities. The former are rigidly translated on the vertical axis, while the latter are multiplied by a constant factor to match the experimental 0 K value.

the distribution of data points. On the other hand, for the trigonal deformation, a fourth-order bivariate polynomial (i.e., 16 parameters) is needed. As an illustration, we report the vibrational energy landscape at 750 K for the tetragonal and for the trigonal distortions (Fig. 10).

### 3. Evaluation of the elastic constants

Next, we sum the static and vibrational energy landscapes obtained in the previous sections and compute the Helmholtz free energy. An example of the resulting landscape at 500 K is displayed in Fig. 11. The second derivative with respect to strain can be evaluated analytically at the minimum of the free energy as a function of temperature.

Then, in order to understand if the discrepancy between the experimental and calculated elastic constants could be ascribed

to the fitting procedure, we have calculated the confidence interval of  $C_{11}$  and  $C_{44}$ . Toward that end, we have computed the covariance matrix of each best-fit contribution to the free energy, defined as

$$\text{cov}(P) = \sigma_r^2 (J^T J)^{-1}, \quad (10)$$

where  $P$  is the set of polynomial coefficients,  $\sigma_r^2$  is the squared residual, and  $J$  is the Jacobian matrix, which is provided in output by the least-squares routine. The global variance of each best-fit polynomial is then obtained by considering both the diagonal and the off-diagonal elements of the covariance matrix  $\text{cov}(P)$ . Finally, we used error-propagation theory to obtain the confidence interval of the elastic constants.

The calculated  $C_{11}$  and  $C_{44}$  elastic constants of bcc  $\alpha$ -iron both decrease by increasing temperature, as shown in Fig. 12. Our results are in reasonable accordance with those reported in Ref. [67] (the exception is  $C_{44}$ , which in our case is fairly underestimated) where, however, a direct detailed comparison with experimental thermal softening is clearly more difficult. In Table III, we report our calculated  $B$ ,  $C_{11}$ , and  $C_{44}$  values with and without zero-point energy (ZPE) corrections, thus comparing them to experimental data. Also, for the sake of completeness, we report in Fig. 13 the temperature dependence of the  $C'$  and in Table IV the  $C_{12} = (3B - C_{11})/2$ ,  $C' = 1/2(C_{11} - C_{12}) = 3/4(C_{11} - B)$ , and anisotropy ratio  $C_{44}/C'$  as from standard theory of elasticity. The inclusion of the ZPE results in a small decrease of the elastic constants and bulk modulus. The confidence intervals at zero temperature are of the order of 0.1 GPa and cannot account for the differences with respect to experiments, so we will discuss other possible sources for such discrepancies in the next section.

### C. Discussion

The temperature dependences of the bulk modulus and of the elastic constants display an overall good agreement with the available experimental data, showing how lattice vibrations alone provide a robust description of the thermoelastic properties of the material, especially below the Debye temperature  $\Theta_D$ . The agreement is still valid above  $\Theta_D$  for the  $C_{44}$ , which shows a near-linear behavior generally expected for metallic systems according to the semiempirical Varshni equation [68]. On the other hand, approaching the Curie temperature (1043 K) from below, the results are not able to reproduce the anomalous nonlinear softening that is observed in experimental  $C'$ ,  $B$  and  $C_{11}$ .

According to previous work, e.g., based on a tight-binding approximation coupled to a single-site spin-fluctuation theory of band magnetism [63], effective spin-lattice couples models [64], as well as experiments [25,26], the origin of these anomalies is inherently related to magnetic fluctuations and, ultimately, to their influence on the free-energy landscape (via modulation of the exchange couplings, configurational disorder, and magnon-phonon interaction). In support of this conclusion, previous *ab initio* papers [11,23] suggest that the electronic entropy and phonon-phonon anharmonic effects beyond the quasiharmonic approximation play a minor role in determining the thermodynamics of the system below  $T_C$ . Given the strong indications of the pivotal role of magnetism

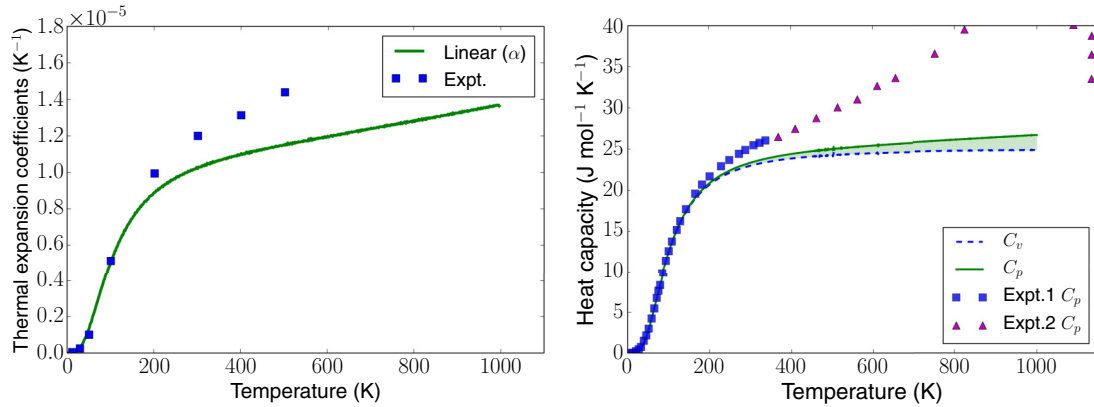


FIG. 7. (Color online) (Left panel) Linear (green solid line) coefficient of thermal expansion compared to experimental data from Ref. [60] (squares). (Right panel) Specific heat at constant pressure (green solid line), at constant volume (blue dashed line), and compared to experimental data from Ref. [61] (Expt. 1, squares) and from Ref. [62] (Expt. 2, triangles).

in the description of thermoelastic properties of  $\alpha$ -iron close to the Curie temperature, further *ab initio* calculations taking into account magnetic disorder would be of paramount interest (see, for instance, Ref. [24]).

Focusing instead on the 0 K structural and elastic properties, we now discuss the possible origin of the mismatch between the calculated and experimental values. As we showed earlier, our calculated points are numerically accurate, and the errors associated with the fit are fairly small. As a consequence, we propose and analyze here three further plausible sources of the mentioned discrepancy, namely, (i) the presence of magnetic domain walls, (ii) the pseudopotential approximation, and (iii) the approximate XC functional.

First, we inspected the possible effects on the equilibrium volume at 0 K of the bcc crystal in the presence of magnetic domain walls. We focus our attention on the collinear magnetic domain wall case, considering a configuration of 8-atoms-thick ferromagnetic layers stacked in the  $z$  direction having alternating antiparallel magnetic polarization. The effect of the sharp interfaces replicated via periodic boundary

conditions along  $z$  results in an increase of about 0.7% of the lattice parameter and, conversely, in a decrease of about 9% of the bulk modulus. However, since the density of domain walls in real materials is expected to be an order of magnitude lower than our simulations, the effect on the lattice parameter should be rescaled accordingly, thus suggesting that this kind of sharp domain walls affects only marginally the 0 K lattice parameter.

Next, we have observed that, for a given XC functional, details of the pseudopotential can have a large impact on the calculated quantities (see Figs. 1 and 2). For instance, for the PBE functional, the bulk modulus at 0 K ranges from 170 to

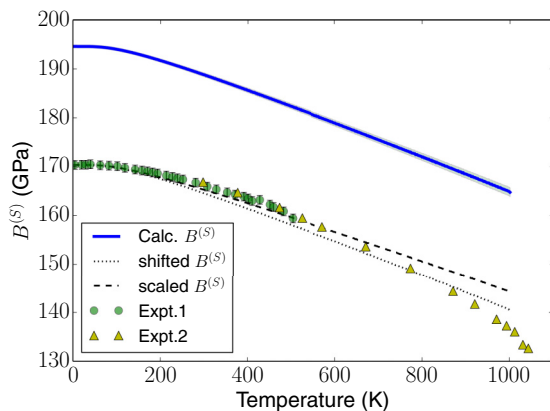


FIG. 8. (Color online) Adiabatic bulk modulus as a function of  $T$  (blue continuous line) calculated along with its confidence interval on the fit (shaded green) and compared to experimental data from Ref. [50] (Expt. 1, green circles) and from Ref. [26] (Expt. 2, yellow triangles). As a guide to the eye, we also plot the bulk modulus rigidly shifted (dotted line) and scaled (dashed line) to match the experimental 0 K value.

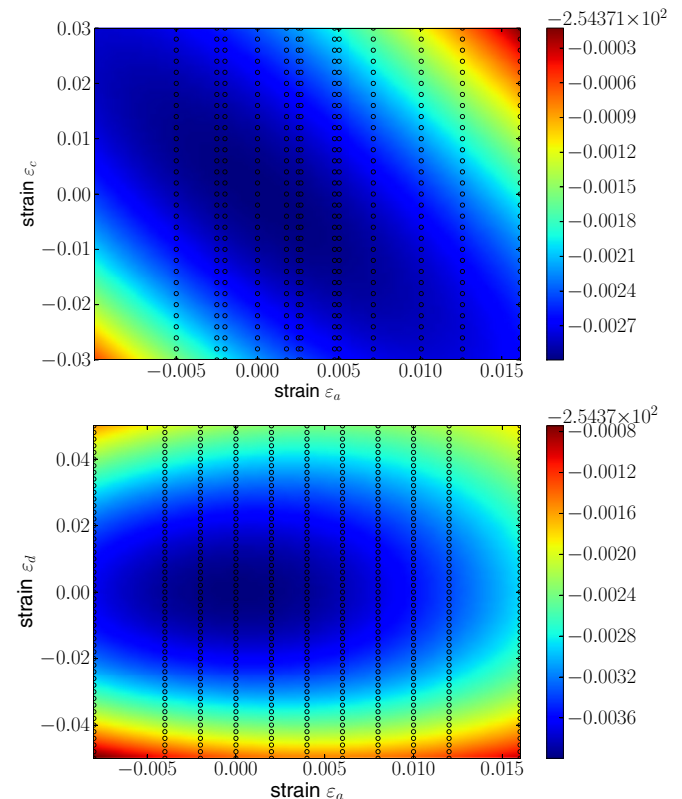


FIG. 9. (Color online) Static energy landscape of the tetragonal (top panel) and trigonal (bottom panel) distortions projected on the  $[\varepsilon_a, \varepsilon_c/d]$  plane.

TABLE II. Average absolute error (AAE) and adjusted coefficient of determination ( $R^2$ ) of the two-dimensional fit of the static energy landscape, for the tetragonal and trigonal deformations, as a function of the order of the polynomial.

Order	tetragonal		trigonal	
	AAE (Ry)	$R^2$	AAE (Ry)	$R^2$
2	$1.894 \times 10^{-5}$	0.997259	$9.163 \times 10^{-5}$	0.971580
3	$1.997 \times 10^{-6}$	0.999975	$7.369 \times 10^{-6}$	0.999819
4	$1.002 \times 10^{-6}$	0.999993	$2.933 \times 10^{-6}$	0.999968
5	$9.150 \times 10^{-7}$	0.999995	$1.693 \times 10^{-6}$	0.999990

200 GPa depending on the pseudopotential generation scheme: ultrasoft or PAW pseudopotentials, with or without semicore electrons in valence, using the same electronic configuration but different pseudization methods, or even different versions of the *pslibrary* [33].

As discussed in Sec. III, the pseudopotential used in this work was chosen as being closest in its equation of state and its magnetization as a function of volume to all-electron FLAPW calculations [45–47,51]. As a result, the discrepancy at 0 K with respect to experiments found in this work and in all-electron calculations seems ascribable mainly to the exchange-

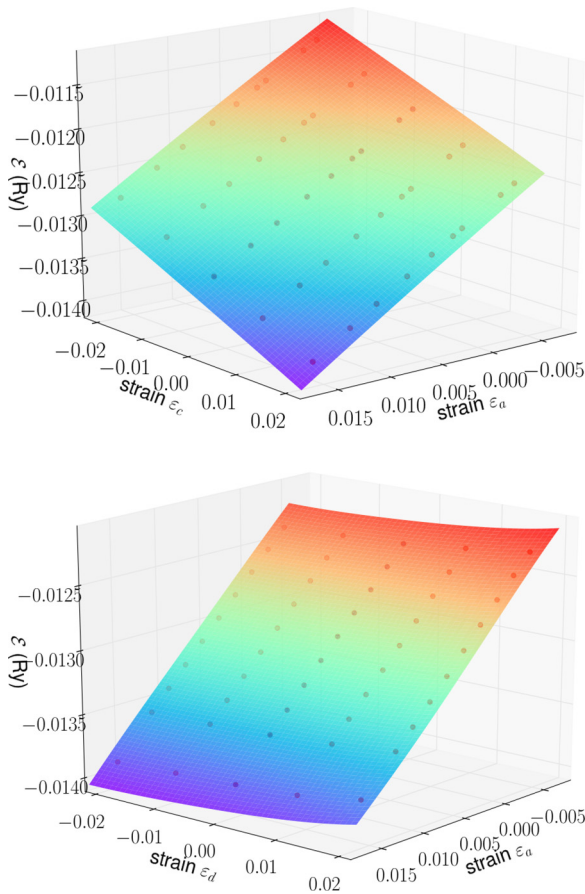


FIG. 10. (Color online) Vibrational quasiharmonic contribution to the Helmholtz free energy at  $T = 750$  K in the  $[\varepsilon_a, \varepsilon_c]$  space (top panel) and the  $[\varepsilon_a, \varepsilon_d]$  space (bottom panel). A second- and fourth-order bivariate polynomial are used, respectively, to fit the tetragonal and trigonal data sets.

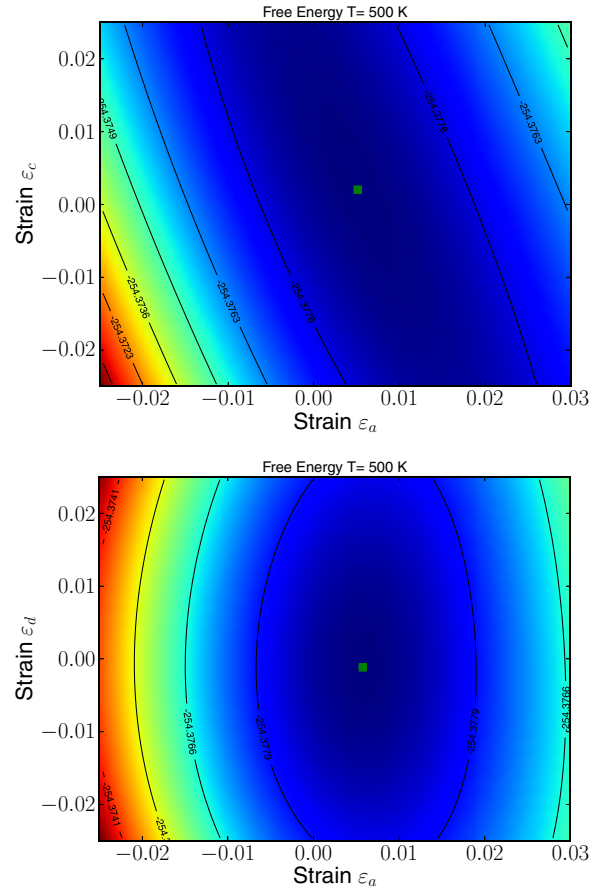


FIG. 11. (Color online) Free-energy landscape of the tetragonal (top panel) and trigonal (bottom panel) deformations projected on the  $[\varepsilon_a, \varepsilon_c]$  and  $[\varepsilon_a, \varepsilon_d]$  plane, respectively, at 500 K. The green squares represent the minima of the energy landscapes.

correlation functional used. For this reason, we explored the effect of the XC functional on the 0 K properties, keeping the pseudopotential generation scheme and parameters unchanged. We performed test calculations with the WC [41] and PBEsol [42] functionals, and we found that the disagreement with the experimental data is increased (see Figs. 1 and 2).

Eventually, we observe that the QHA thermal contribution to the energy landscape is almost linear (see Fig. 10) and does not contribute too much to the total curvature in the energy landscape. Moreover, its change in second derivative along with temperature is even smaller, and contributes only marginally to the temperature dependence of the total curvature of the energy landscape (its main effect is to shift the minimum of the free energy as a function of temperature). Therefore,

TABLE III. Calculated 0 K elastic constants for iron with and without zero-point energy contributions. Results are compared to experimental data extrapolated to 0 K.

$T$ (K)	$a$ (Å)	$B$ (GPa)	$C_{11}$ (GPa)	$C_{44}$ (GPa)
0 (no ZPE)	2.834	$199.8 \pm 0.1$	$296.7 \pm 0.3$	$104.7 \pm 0.1$
0 (ZPE)	2.839	$194.6 \pm 0.3$	$287.9 \pm 0.4$	$102.2 \pm 0.5$
0 (Expt.) [36,50]	2.856	$170.3 \pm 1$	$239.5 \pm 1$	$120.7 \pm 0.1$



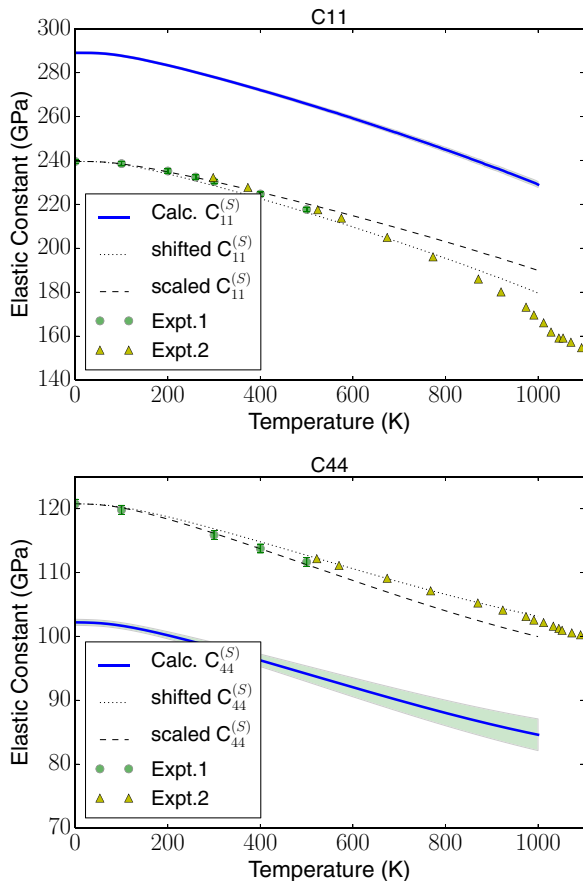


FIG. 12. (Color online) Top panel: calculated adiabatic  $C_{11}$  elastic constant (blue solid line). Bottom panel: calculated adiabatic  $C_{44}$  (blue solid line). Two sets of experimental data are reported on each plot: Expt. 1 (green circles) from Ref. [50] and Expt. 2 (yellow triangles) from Ref. [26]. The calculated interval of confidence is displayed as a shaded area. As a guide to the eye, we also plot the elastic constants rigidly shifted (dotted line) and scaled (dashed line) to match the experimental values at zero temperature.

we conclude first that the mismatch with experiments at finite temperature is dominated by the 0 K static contribution discussed above, and second that the temperature dependence of the elastic constants is driven, in first approximation, by the curvature of the 0 K energy landscape at the equilibrium expanded volumes. Our finding suggests that one could try and employ more computationally expensive methods (such as DFT+U+J [40,69], hybrid functionals [70], RPA [71,72], or DMFT [73,74]) to explore possible improvements in the

TABLE IV.  $C_{12}$  and  $C'$  elastic constants, and  $C_{44}/C'$  anisotropy ratio, derived from Table III with and without zero-point energy. Results are compared to experimental data extrapolated at 0 K. Errors are obtained according to propagation of uncertainties.

$T$ (K)	$C_{12}$ (GPa)	$C'$ (GPa)	$C_{44}/C'$
0 (no ZPE)	$151.4 \pm 0.2$	$72.7 \pm 0.3$	1.44
0 (ZPE)	$148.01 \pm 0.5$	$70.0 \pm 0.4$	1.46
0 (Expt.) [50]	135.7	51.9	2.32

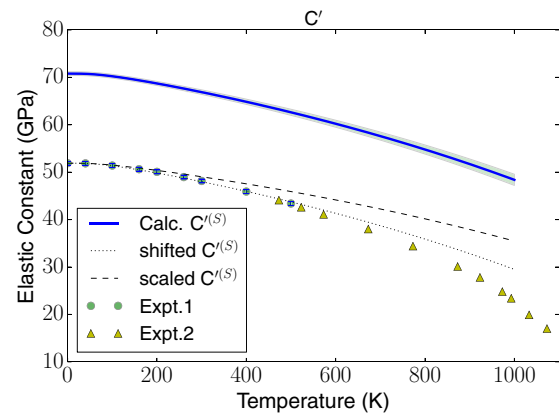


FIG. 13. (Color online) Thermal behavior of the  $C'$  elastic constant calculated as a linear combination of  $B(T)$  and  $C_{11}(T)$  (blue continuous line). Two sets of experimental data are reported: Expt. 1 (green circles) from Ref. [50] and Expt. 2 (yellow triangles) from Ref. [26]. The calculated interval of confidence is displayed as a shaded area. As a guide to the eye, we also plot the elastic constants rigidly shifted (dotted line) and scaled (dashed line) to match the experimental values at zero temperature.

description of the 0 K mechanical properties of  $\alpha$ -iron, while thermal properties can be determined using lattice dynamics calculations performed with standard semilocal GGA functionals.

## V. CONCLUSIONS

We have calculated the isothermal and adiabatic elastic constants of  $\alpha$ -iron as a function of temperature from first-principles, using pseudopotential total energy calculations based on DFT and lattice-dynamics calculations based on DFPT, out of which we calculate free energies in the quasiharmonic approximation and finite-temperature elastic constants from small strain deformations. Great care has been put into the verification of the pseudopotentials, and the validation of the results against experiments. Common semilocal DFT functionals such as PBE reproduce only fairly elastic constants at zero temperature; on the other hand, their thermal behavior, originating from the changes in phonon dispersions upon crystal expansion, is very well described by the same functionals and in the quasiharmonic approximation, with a softening of the elastic constants and bulk modulus that is in excellent agreement with experiments up to  $\Theta_D$  and above.

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